



## 17DCT - High torque for demanding applications

- ✓ High power density
- ✓ Increased battery life
- ✓ Cost effective motion solution
- ✓ Better efficiency

Our DCT family of Athlonix Brush DC mini motors introduces the new 17DCT high torque motor. 17DCT Athlonix Brush DC motors can reach a torque of 6.14mNm with 86% efficiency while maintaining long life, all while providing a low cost of ownership. Athlonix 17DCT miniature dc motors are available in 2 variations, precious metal commutation and graphite commutation with a Neodymium magnet inside. With these power packed features, our new Athlonix 17DCT motors are ideally suited for use in performance-critical applications in markets such as medical, power hand tools, robotics and others.

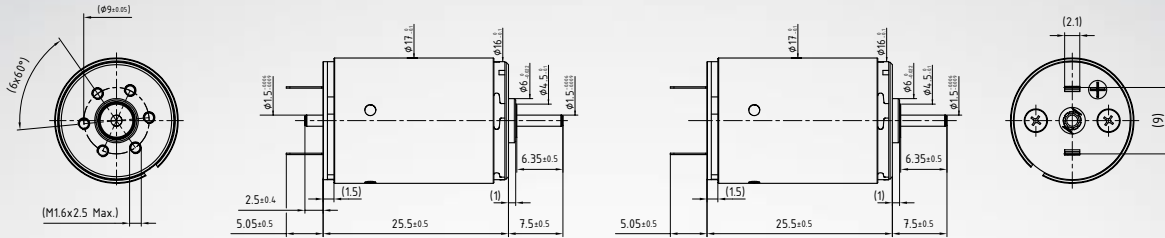
### OUTPUT AND PERFORMANCE

- Max continuous torque up to 6.14 mNm
- Output power up to 4.8W
- Efficiency up to 86%

### KEY FEATURES

- High continuous torque enhances power density of the overall composite
- Higher battery life ensures lower cost of ownership for battery operated applications
- Component standardization and design modularity ensures quick customization capability for samples across various applications
- Graphite commutation also available, utilizing a unique constant force spring design ensuring consistent performance throughout the life of the motor
- Option of having REE coil which ensures extended life of the motor and provides an environment of intrinsic safety especially at high speed conditions

Medical: Infusion pumps, imaging machines, medical analyzers	Robotics: Humanoid robots	Other: Power hand tools	Other: Rotary tattoo machines
			

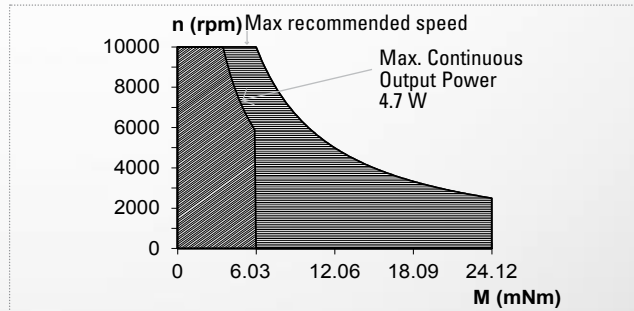


**Dimensions in mm**

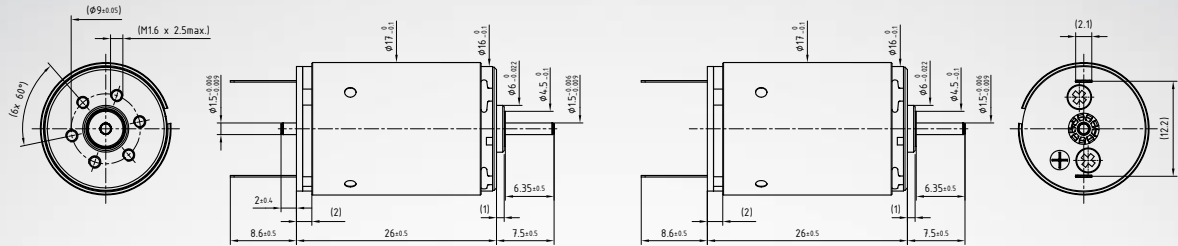
**17DCT 26P1/P2 \*\*\*\* \***

Electrical Data		****	209E	205P	107P	205E	
1	Nominal Voltage	V	18	24	36	48	Volt
2	No-Load Speed	$n_o$	8030	7769	9800	8145	rpm
3	No-Load Current	$I_o$	4.2	3.1	2.6	1.6	mA
4	Terminal Resistance	R	30.7	51.4	76.0	208.1	$\Omega$
5	Output Power	$P_{2max}$	4.5	4.8	4.7	4.6	W
6	Stall Torque	mNm	12.36 (1.76)	13.6 (1.93)	16.43 (2.33)	12.8 (1.82)	mNm (oz-in)
7	Efficiency	$\eta_{max}$	84	84	86	84	%
8	Max Continuous Speed	$n_{e,max}$	10000	10000	10000	10000	rpm
9	Max Continuous Torque	$M_{e,max}$	5.75 (0.82)	6.14 (0.87)	6 (0.85)	5.8 (0.83)	mNm (oz-in)
10	Max Continuous Current	$I_{e,max}$	0.27	0.21	0.17	0.11	A
11	Back-EMF Constant	$k_E$	2.23	3.07	3.65	5.85	mV/rpm
12	Torque Constant	$k_M$	21.25	29.31	34.89	55.88	mNm/A
13	Motor Regulation	$R/k^2$	68.01	59.79	62.45	66.62	$10^3/Nms$
14	Friction Torque	$T_F$	0.08 (0.02)	0.08 (0.02)	0.08 (0.02)	0.08 (0.02)	mNm (oz-in)
15	Mechanical Time Constant	$\tau_m$	7.06	6.23	6.22	7.04	ms
16	Rotor Inertia	J	1.04	1.04	1.00	1.01	g.cm <sup>2</sup>
General Data							
17	Thermal Resistance (rotor/body)	$R_{th1} / R_{th2}$		6/25			$^{\circ}C/W$
18	Thermal Time Constant (rotor/stator)	$\tau_{w1} / \tau_{w2}$		12/250			S
19	Operating Temperature Range:	$\tau_{w1} / \tau_{w2}$		-30°C to 85°C (-22°F to 185°F)			$^{\circ}C$ ( $^{\circ}F$ )
		rotor		100°C (212°F)			$^{\circ}C$ ( $^{\circ}F$ )
20	Shaft Load Max:			With sleeve bearings			
	(5mm from bearing)	-radial		1.5 (5.39)			N (oz)
		-axial		100 (359.6)			N (oz)
21	Shaft Play:	-radial		0.03 (0.0012)			mm (inch)
		-axial		0.15 (0.0059)			mm (inch)
22	Weight	g		27 (0.96)			g (oz)

Execution Table			
Gearbox	Single Shaft	MR2	M Sense B
R16	1	2	Upon Request
B16	3	4	Upon Request
BA16	3	4	Upon Request



**Note:**  
**P1** : standard commutation  
**P2** : special commutation for double shaft version

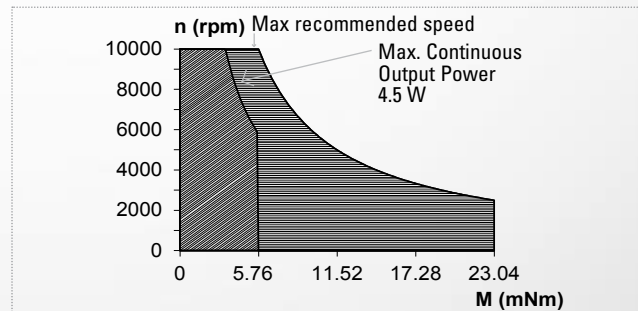


Dimensions in mm

17DCT 26G1/G2 \*\*\*\* \*

Electrical Data	****	209E	205P	107P	205E	
1 Nominal Voltage	V	18	24	36	48	Volt
2 No-Load Speed	$n_o$	7869	7628	9653	7988	rpm
3 No-Load Current	$I_o$	15.8	11.5	9.6	6.0	mA
4 Terminal Resistance	R	30.8	51.5	76.1	208.2	Ω
5 Output Power	$P_{2max}$	4.3	4.6	4.5	4.4	W
6 Stall Torque	mNm	12.07 (1.71)	13.33 (1.89)	16.16 (2.29)	12.55 (1.78)	mNm (oz-in)
7 Efficiency	$\eta_{max}$	70	71	73	70	%
8 Max Continuous Speed	$n_{e,max}$	10000	10000	10000	10000	rpm
9 Max Continuous Torque	$M_{e,max}$	5.49 (0.78)	5.88 (0.84)	5.75 (0.82)	5.56 (0.79)	mNm (oz-in)
10 Max Continuous Current	$I_{e,max}$	5.49	5.88	5.75	5.56	A
11 Back-EMF Constant	$k_E$	2.23	3.07	3.65	5.85	mV/rpm
12 Torque Constant	$k_M$	21.25	29.31	34.89	55.88	mNm/A
13 Motor Regulation	$R/k^2$	68.23	59.91	62.53	66.65	10 <sup>3</sup> /Nms
14 Friction Torque	$T_F$	0.3 (0.05)	0.3 (0.05)	0.3 (0.05)	0.3 (0.05)	mNm (oz-in)
15 Mechanical Time Constant	$\tau_m$	7.08	6.24	6.23	7.04	ms
16 Rotor Inertia	J	1.04	1.04	1.00	1.06	g.cm <sup>2</sup>
<b>General Data</b>						
17 Thermal Resistance (rotor/body)	$R_{th1} / R_{th2}$			6/25		°C/W
18 Thermal Time Constant (rotor/stator)	$\tau_{w1} / \tau_{w2}$			12/250		S
19 Operating Temperature Range:	$\tau_{w1} / \tau_{w2}$			-30°C to 85°C (-22°F to 185°F)		°C (°F)
	rotor			100°C (212°F)		°C (°F)
20 Shaft Load Max: (5mm from bearing)				With sleeve bearings		
	-radial			1.5 (5.39)		N (oz)
	-axial			100 (359.6)		N (oz)
21 Shaft Play:	-radial			0.03 (0.0012)		mm (inch)
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Note:

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— Continuous Working Range  
 — Intermittent Working Range

**Athlonix™**

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